

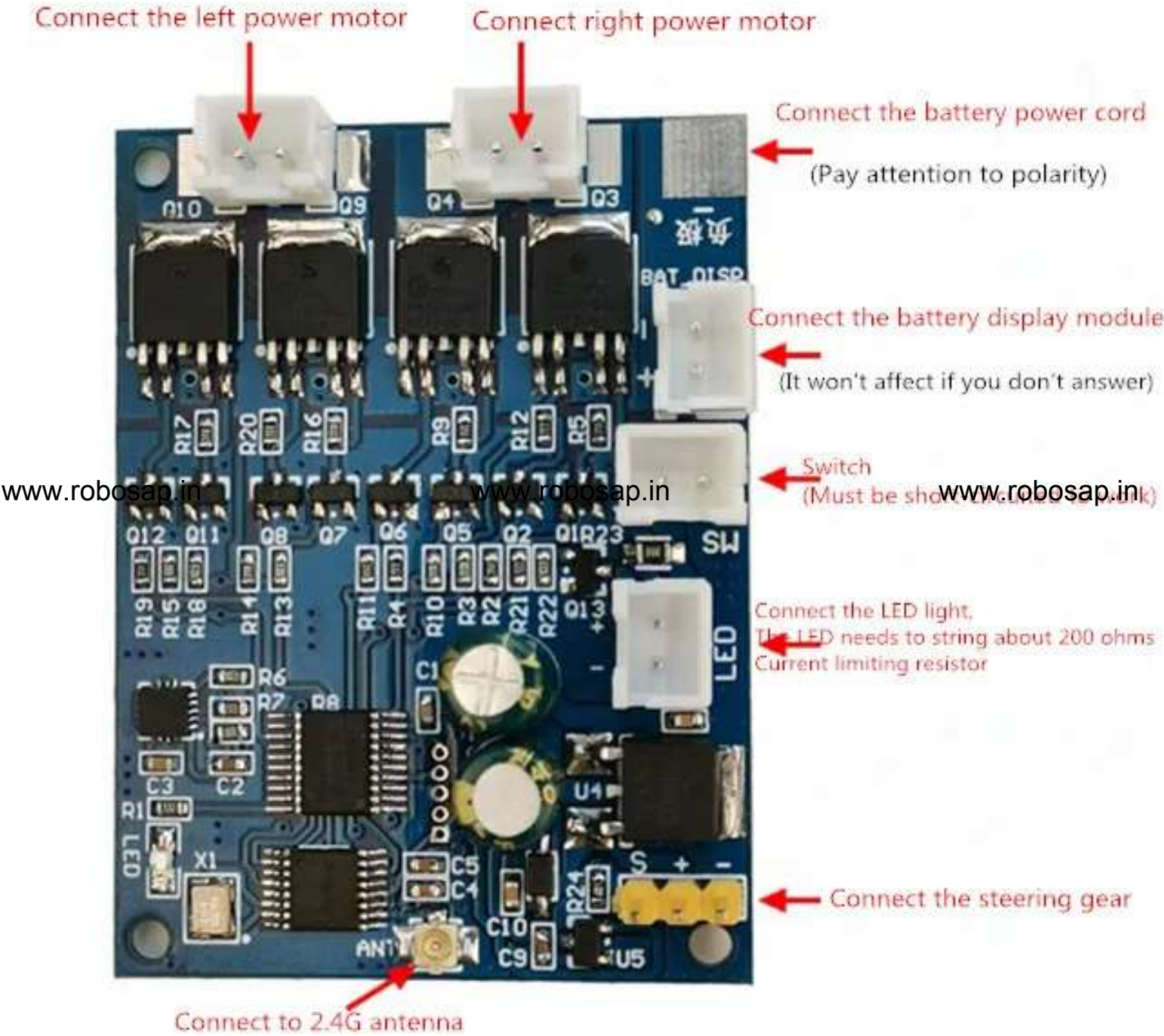


Excluding DC line and antenna

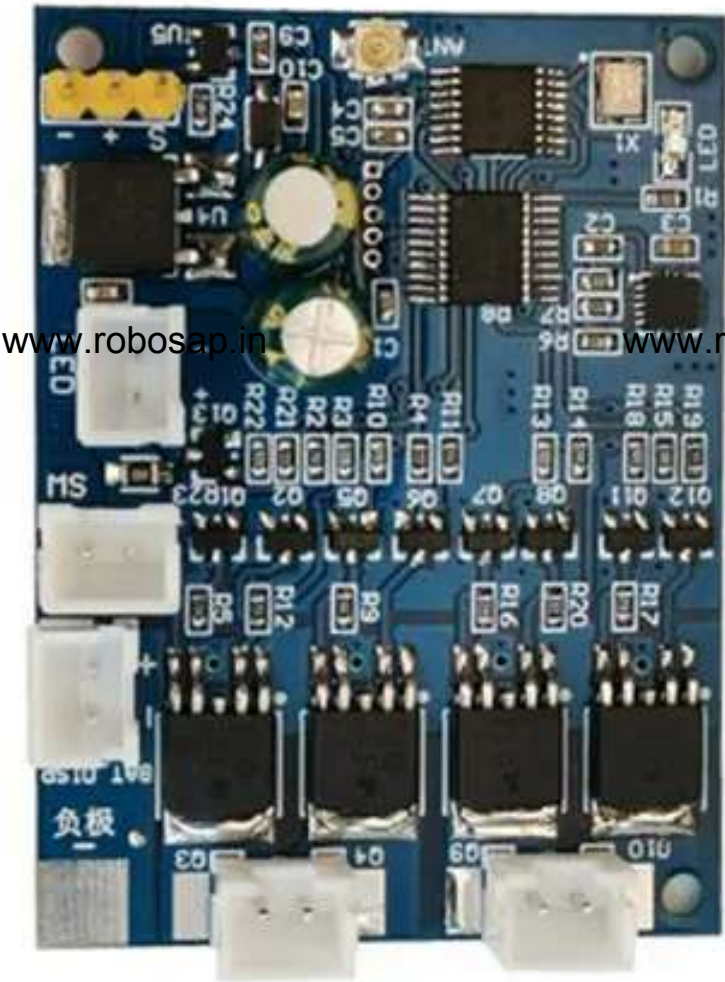
Suitable for rebuilding and maintenance of nesting boats



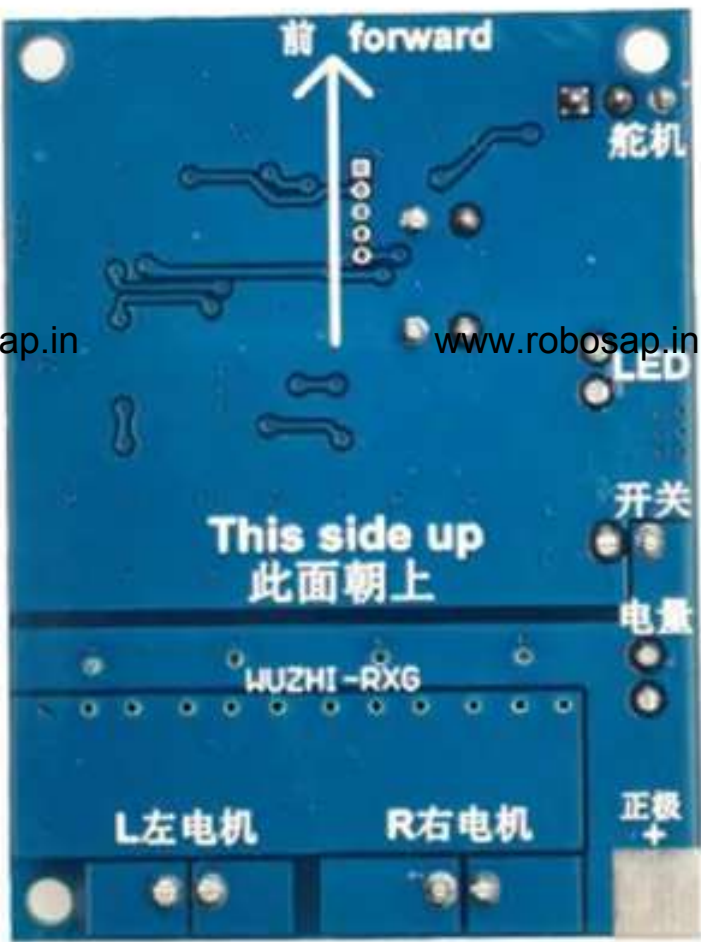




Note: The motherboard has a built-in gyroscope chip, please install it in the direction indicated on the back of the motherboard, so that the hull can realize automatic straight-line driving



positive



back



Code

Remote control off

Keep pressing the cruise control button

Turn on the remote control switch at the same time

The remote control indicator flashes to enter the code matching mode

At this time, power on the receiving board again

The indicator light becomes steady

Code completion

If there is no receiving board within 20 seconds, power on again and check the code on the remote control

The remote control automatically jumps out of the code matching mode



Cruise control

Remote control hull driving at a certain speed

Press the cruise button at the same time, the model automatically presses this speed

Cruise control, press the +- button to fine-tune the cruise speed

In cruise control mode, press the cruise control button

Exit cruise mode

Accelerate or turn at the same time in cruise mode

Enter calibration mode

(Pay attention to first connect the receiving board lighting, see the instructions)



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Handle down to the end

Press the three buttons indicated in the figure at the same time

The remote control has a beep

And the light on the receiving board starts to flash to enter the calibration mode

Pull the left and right handles to the side at the same time

Press the two buttons indicated in the figure at the same time

The remote control has a beep

And the light on the receiving board starts to flicker and enter the calibration mode

Gyro zero calibration



In calibration mode

Keep the hull still

Don't shake

Press the cruise control button

The receiving board lighting is always on for 3 seconds

Zero point calibration completed

Under what circumstances is zero point calibration required?

If the hull moves in a straight line, it has been offset in one direction

When the deviation is severe

Need zero point calibration

Servo angle selection



In calibration mode

Press the button shown in the figure to adjust the angle of the servo

The angle value will be saved after selection

Not lost when power off

5 angles can be selected

They are 30, 45, 60, 75, 90 degrees

There will be a demonstration of the itinerary when the angle is selected

Gyro sensitivity adjustment



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In calibration mode

Press the +- button as shown in the figure to adjust the sensitivity of the gyroscope
Under what circumstances do you need sensitivity?

When the model moves in a straight line, the bow of the ship sways left and right

Need to reduce sensitivity

In calibration mode
Press the +- button as shown in the figure to adjust the sensitivity of the gyroscope

Under what circumstances do you need sensitivity?

When the model moves in a straight line, the bow of the ship sways left and right

Need to reduce sensitivity

(Exit calibration mode)

One-handed remote control press the OK button as shown in the figure
(Illumination button)

Exit calibration mode

Use the two-handed remote control to press the lighting control button as shown in the figure,

Exit calibration mode